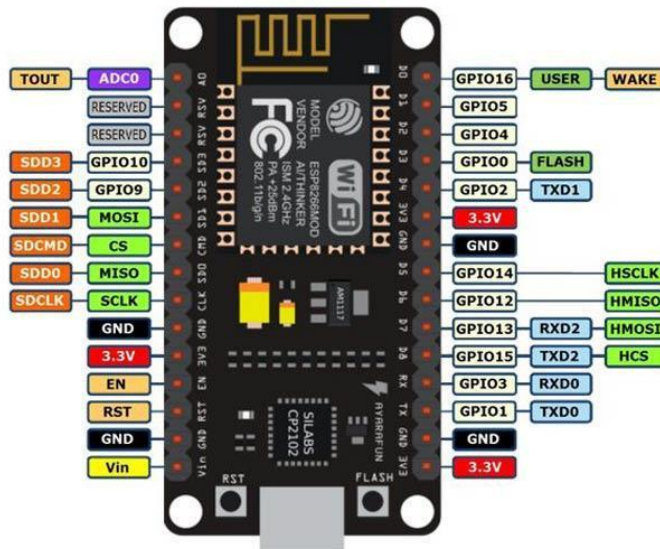


Lampiran

1. NodeMCU esp8266

Spesifikasi NodeMCU ESP8266 yang terbaru adalah sebagai berikut.

1. Mikrokontroler: Tensilica 32-bit RISC CPU Xtensa LX106
2. Tegangan operasi: 3.3V
3. Tegangan Masukan: 7-12V
4. Pin Digital I/O (DIO): 16
5. Pin Analog Input (ADC): 1
6. UARTs: 2
7. SPIs: 1
8. I2Cs: 1
9. Flash Memory: 4 MB
10. SRAM: 64 KB
11. Clock Speed: 80 MHz
12. PCB Antenna

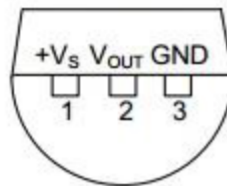


2. LM35

**NDV Package
3-Pin TO-CAN
(Top View)**

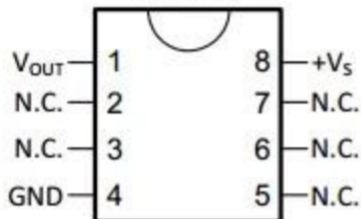


**LP Package
3-Pin TO-92
(Bottom View)**



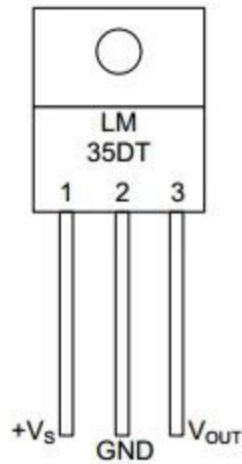
Case is connected to negative pin (GND)
Refer the second NDV0003H page for
reference

**D Package
8-PIN SOIC
(Top View)**



N.C. = No connection

**NEB Package
3-Pin TO-220
(Top View)**



Pin Functions

NAME	PIN				TYPE	DESCRIPTION
	TO46	TO92	TO220	SO8		
V _{OUT}	2	2	3	1	O	Temperature Sensor Analog Output
N.C.	—	—	—	2	—	No Connection
	—	—	—	3		
GND	3	3	2	4	GROUND	Device ground pin, connect to power supply negative terminal
N.C.	—	—	—	5	—	No Connection
	—	—	—	6		
	—	—	—	7		
+V _S	1	1	1	8	POWER	Positive power supply pin

6 Specifications

6.1 Absolute Maximum Ratings

over operating free-air temperature range (unless otherwise noted)⁽¹⁾⁽²⁾

	MIN	MAX	UNIT
Supply voltage	-0.2	35	V
Output voltage	-1	6	V
Output current		10	mA
Maximum Junction Temperature, T_{Jmax}		150	°C
Storage Temperature, T_{stg}	TO-CAN, TO-92 Package	-60	150
	TO-220, SOIC Package	-65	150

- (1) If Military/Aerospace specified devices are required, please contact the Texas Instruments Sales Office/ Distributors for availability and specifications.
(2) Absolute Maximum Ratings indicate limits beyond which damage to the device may occur. DC and AC electrical specifications do not apply when operating the device beyond its rated operating conditions.

6.2 ESD Ratings

	VALUE	UNIT
$V_{(ESD)}$ Electrostatic discharge	Human-body model (HBM), per ANSI/ESDA/JEDEC JS-001 ⁽¹⁾	±2500

- (1) JEDEC document JEP155 states that 500-V HBM allows safe manufacturing with a standard ESD control process.

6.3 Recommended Operating Conditions

over operating free-air temperature range (unless otherwise noted)

	MIN	MAX	UNIT
Specified operating temperature: T_{MIN} to T_{MAX}	LM35, LM35A	-55	150
	LM35C, LM35CA	-40	110
	LM35D	0	100
Supply Voltage (+ V_S)	4	30	V

6.4 Thermal Information

THERMAL METRIC ⁽¹⁾⁽²⁾	LM35				UNIT
	NDV	LP	D	NEB	
	3 PINS		8 PINS	3 PINS	
$R_{\theta JA}$ Junction-to-ambient thermal resistance	400	180	220	90	°C/W
$R_{\theta JC(top)}$ Junction-to-case (top) thermal resistance	24	—	—	—	

6.5 Electrical Characteristics: LM35A, LM35CA Limits

Unless otherwise noted, these specifications apply: $-55^{\circ}\text{C} \leq T_J \leq 150^{\circ}\text{C}$ for the LM35 and LM35A; $-40^{\circ}\text{C} \leq T_J \leq 110^{\circ}\text{C}$ for the LM35C and LM35CA; and $0^{\circ}\text{C} \leq T_J \leq 100^{\circ}\text{C}$ for the LM35D. $V_S = 5\text{ Vdc}$ and $I_{LOAD} = 50\ \mu\text{A}$, in the circuit of [Full-Range Centigrade Temperature Sensor](#). These specifications also apply from 2°C to T_{MAX} in the circuit of [Figure 14](#).

PARAMETER	TEST CONDITIONS	LM35A			LM35CA			UNIT
		TYP	TESTED LIMIT ⁽¹⁾	DESIGN LIMIT ⁽²⁾	TYP	TESTED LIMIT ⁽¹⁾	DESIGN LIMIT ⁽²⁾	
Accuracy ⁽³⁾	$T_A = 25^{\circ}\text{C}$	±0.2	±0.5		±0.2	±0.5		
	$T_A = -10^{\circ}\text{C}$	±0.3			±0.3		±1	
	$T_A = T_{MAX}$	±0.4	±1		±0.4	±1		
	$T_A = T_{MIN}$	±0.4	±1		±0.4		±1.5	
Nonlinearity ⁽⁴⁾	$T_{MIN} \leq T_A \leq T_{MAX}$, $-40^{\circ}\text{C} \leq T_J \leq 125^{\circ}\text{C}$	±0.18		±0.35	±0.15		±0.3	
Sensor gain (average slope)	$T_{MIN} \leq T_A \leq T_{MAX}$	10	9.9		10		9.9	
	$-40^{\circ}\text{C} \leq T_J \leq 125^{\circ}\text{C}$	10	10.1		10		10.1	
Load regulation ⁽⁵⁾ $0 \leq I_L \leq 1\text{ mA}$	$T_A = 25^{\circ}\text{C}$	±0.4	±1		±0.4	±1		
	$T_{MIN} \leq T_A \leq T_{MAX}$, $-40^{\circ}\text{C} \leq T_J \leq 125^{\circ}\text{C}$	±0.5		±3	±0.5		±3	
Line regulation ⁽⁵⁾	$T_A = 25^{\circ}\text{C}$	±0.01	±0.05		±0.01	±0.05		
	$4\text{ V} \leq V_S \leq 30\text{ V}$, $-40^{\circ}\text{C} \leq T_J \leq 125^{\circ}\text{C}$	±0.02		±0.1	±0.02		±0.1	
Quiescent current ⁽⁶⁾	$V_S = 5\text{ V}$, 25°C	56	67		56	67		
	$V_S = 5\text{ V}$, $-40^{\circ}\text{C} \leq T_J \leq 125^{\circ}\text{C}$	105		131	91		114	
	$V_S = 30\text{ V}$, 25°C	56.2	68		56.2	68		
	$V_S = 30\text{ V}$, $-40^{\circ}\text{C} \leq T_J \leq 125^{\circ}\text{C}$	105.5		133	91.5		116	
Change of quiescent current ⁽⁵⁾	$4\text{ V} \leq V_S \leq 30\text{ V}$, 25°C	0.2	1		0.2	1		
	$4\text{ V} \leq V_S \leq 30\text{ V}$, $-40^{\circ}\text{C} \leq T_J \leq 125^{\circ}\text{C}$	0.5		2	0.5		2	
Temperature coefficient of quiescent current	$-40^{\circ}\text{C} \leq T_J \leq 125^{\circ}\text{C}$	0.39		0.5	0.39		0.5	
Minimum temperature for rate accuracy	In circuit of Figure 14 , $I_L = 0$	1.5		2	1.5		2	
Long term stability	$T_J = T_{MAX}$, for 1000 hours	±0.08			±0.08			

3. YL-69

SOIL MOISTURE RECORDER SPECIFICATIONS

Data Recorder	Soil Moisture Probes
Measurement Range: +/- 1200mV	Measurement Range: (EC-5) 0 to 100% VWC saturation (EC-20) 0 to 40% VWC saturation
Accuracy: +/-0.01% FSR	Measurement Type: VWC (Volumetric Water Content)
Input range: 0 to 2.5V DC	Measurement Accuracy: (EC-5) +/- 3% typical, ALL soils (EC-20) +/- 4% typical on low EC and medium textured soils (Both models) +/-1% with soil specific calibration
Memory: 32,767 readings; software configurable memory wrap	Calibration: Digital calibration through software
Reading Rate: 1 reading every 2 seconds to 1 every 12 hours	Calibration Date: Automatically recorded within device
Input Connection: Removable screw terminal plug	Life Expectancy (probes): 3-5 years
Operating Environment: -40 to +80°C (-40 to +176°F), 0-95% RH, non-condensing	Measurement Time: 10ms
Battery Type: 3.6V Lithium Battery included; user replaceable	Measurement Resolution: 0.002m ³ /m ³
Battery Life: 10 years typical @ 15 min reading rate	Operating Environment: -40 to +60 degC (-40 to +140 degF), 0-100% RH (EC-5 and EC-20 models)
Dimensions: 0.8"x1.7"x2.7"(21mmx44mmx69mm)	Power Requirement: Powered from data recorder's internal battery. (probes) No external power required.
Weight: 2 oz. (56 g)	Dimensions (probes): (EC-5) 2.1"x0.6"x0.06" (55mm x 15mm x 1.5mm) (Cable length) - 16' (5 m), (tinned, wire leads)
Weatherproof Enclosure: Anodized aluminum case w/mounting flange. Communications port plug 3.5"x2.9"x1.1"(87mmx73mmx27mm) 7 oz. (198 g)	(EC-20) 10"x1.25"x0.06" (255mmx32mm x1.5mm) Cable length) - 16' (5 m), (tinned, wire leads)

SOFTWARE FEATURES

Multiple Graphs: Simultaneously analyze data from several units or deployments; easily switch to a single data series	Statistics: Calculate averages, min, max and standard deviation
Real-Time Recording: Collect and display data in real-time while continuing to log	Export Data: Export data in a variety of common formats, or switch to Excel® with a single click
Data Table: Instantly access tabular view for detailed dates, times, values, and annotations	Calibration: Automatically calculate and store calibration parameters
Scaling Options: Autoscale function fits data to the screen, or allows user to manually enter their own values	Logger Configuration: Easy set up and launch of data loggers with immediate or delayed start, preferred sample rate, and device ID
Printing: Automatically print graphical or tabular data	Communications: Automatic or user-enabled communications port configuration (Baud rate, COM port selection)

4. Breadboard

Solderless Plug-in BreadBoards



Solderless BreadBoard Specifications

BB300 Body Material: White ABS Plastic with Black Printed Legend
BB400/BB830/BB1660 Body Material: White ABS Plastic with Color Printed Legend
BB400T/BB830T/BB1660T Body Material: Transparent ABS Plastic with Color Printed Legend

Hole Pitch/Style: 0.1" (2.54 mm), Square Wire Holes

ABS Heat Distortion Temperature: 84° C. (183° F.)

Spring Clip Contact: Phosphor Bronze with Plated Nickel Finish
Contact Life: 50,000 insertions
Rating: 36 Volts, 2 Amps

Insertion Wire Size: 21 to 26 AWG wire, or 0.025" Square post headers
0.016 to 0.028 inches diameter (0.4 to 0.7mm diameter)

Backing: Peelable adhesive tape for attaching to a surface.
Metal back plates provided with 1660 tie point breadboards.

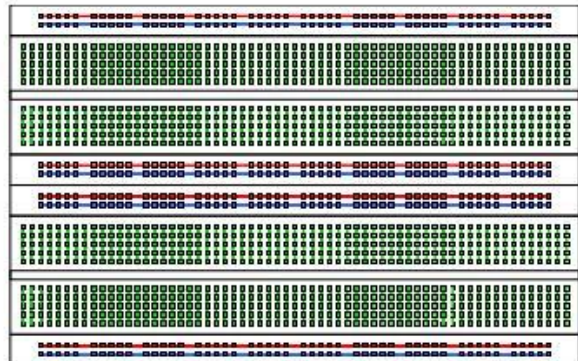
Metal Back Plate Thickness: 0.031 inches (0.8mm)

All BPS BreadBoards are Lead-Free and *RoHS Compliant*.



Internal Connections

The BB1660 and BB1660T breadboards have four rows of 63 vertical columns. Each column has 5 connected holes each (the green lines). This is the circuit area. There are also 8 "rails" (or distribution strips) for power and ground running horizontally (the red and blue lines). A distribution strip can be used to carry a signal if it is not needed for power or ground.



BusBoard Prototype Systems - Built for designers

www.BusBoard.com sales@busboard.com

BPS-DAT-(BB1660)-0001 Rev 1.00 Datasheet.doc

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5. Water Pump motor 220V

Description:

This is Micro Submersible Water Pump DC 3V-5V, can be easily integrate to your water system project. The water pump works using water suction method which drain the water through its inlet and released it through the outlet. You can use the water pump as exhaust system for your aquarium and controlled water flow fountain.

Specification:

Input Voltage: DC 3V-5V

Flow Rate: 1.2-1.6 L/min

Operation Temperature: 80 Deg.C

Operating Current: 0.1-0.2A

Suction Distance: 0.8 meter (Max)

Outside diameter of water outlet: 7.5mm

Inside diameter of water outlet: 5.0 mm

Diameter of water Inlet : 5.0 mm

Wire Length: 200 mm

Size: 45 x 30 x 25 mm

Weight: 30g



Lampiran program

```
#define THINGER_SERIAL_DEBUG

#include <ThingerESP8266.h>
#include <ESP8266WiFi.h>
#include <DHT.h>
#include "arduino_secrets.h"
#include <SimpleTimer.h>
#include <ThingerESP8266.h>
#include <LiquidCrystal_I2C.h>

#define DHTPIN D5 //Pin data dari DHT terhubung ke pin D7 NodeMCU
#define DHTTYPE DHT11
#define CAHAYA D7

DHT dht(DHTPIN, DHTTYPE);
LiquidCrystal_I2C LCD(0x27,16,2); //lcd board
ThingerESP8266 thing(USERNAME, DEVICE_ID,
DEVICE_CREDENTIAL); float hum,temp;
const int pinDigital = A0;
const int relay = D3;
float sensorValue = 0;
String kondisi, kondisia, kondisi_cahaya=
""; SimpleTimer timer;
unsigned long previousMillis = 0;
const long interval = 3000;

void sendSensor()
{ //lcd to android && LCD to board lcd int POT =
analogRead(A0);
```



```

Serial.print(POT);

LCD.setCursor(0,0);LCD.print(" ADC");LCD.setCursor(4,0);LCD.print(POT);LCD
D.print(" ");
LCD.setCursor(0,1);LCD.print("PUMP");

if (POT>500){
Serial.println("KERING");//ke serial monitor
LCD.setCursor(9,0);LCD.print("KERING");
LCD.setCursor(5,1);LCD.print("ON ");
digitalWrite(relay,LOW);
for(int x=0; x<=10; x++){ LCD.setCursor(9,1);LCD.print(x);delay(500);}
LCD.clear();
digitalWrite(relay,HIGH);
LCD.setCursor(0,0);LCD.print(" AIR MERESAP");
LCD.setCursor(0,1);LCD.print(" WAIT");
for(int x=9; x>0; x--){ LCD.setCursor(9,1);LCD.print(x);
delay(500);}
LCD.clear();
}

else if (POT>400&&POT<500){
Serial.println("NORMAL");
LCD.setCursor(9,0);LCD.print("NORMAL");
LCD.setCursor(5,1);LCD.print("OFF");
digitalWrite(relay,HIGH); }

else if (POT<400){
Serial.println("BASAH");
LCD.setCursor(9,0);LCD.print("BASAH ");

```



```
LCD.setCursor(5,1);LCD.print("OFF");
digitalWrite(relay,HIGH);
}
}

void setup() {
  // open serial for monitoring
  Serial.begin(115200); thing.add_wifi(SSID,
  SSID_PASSWORD);
  pinMode(relay,OUTPUT);
  pinMode(CAHAYA, INPUT);
  timer.setInterval(1000L, sendSensor);
  LCD.init();
  LCD.backlight();

  dht.begin();

  thing.add_wifi(SSID, SSID_PASSWORD);
  thing["dht11"] >> [](pson& out){
    out["humidity"] = hum;
    out["celsius"] = temp;
  };
  thing["moisture"] >> [](pson & out) {
    out = analogRead(sensorValue);
  };
  thing["Dataku"] >> [](pson & out){
    out ["kondisi"] = kondisi;};
  thing["Data cahaya"] >> [](pson & out){
    out ["kondisi_cahaya"] = kondisi_cahaya;};

}
```

```

void loop() {
  timer.run();
  thing.handle();

  //sensor membutuhkan waktu 250 ms ketika membaca suhu dan kelembaban
  float h = dht.readHumidity(); //Membaca kelembaban
  float t = dht.readTemperature(); //Membaca suhu dalam satuan Celcius
  float f = dht.readTemperature(true); //Membaca suhu dalam satuan Fahrenheit

  hum = h;
  temp = t;
  delay(1000);
  Serial.print("Suhu: ");
  Serial.print(t);
  Serial.println (" *C ");
  unsigned long currentMillis = millis();
  if(currentMillis - previousMillis >=
  interval) {
    previousMillis = currentMillis;
    int POT = analogRead(A0);
    int cahaya = digitalRead(CAHAYA);

    if(cahaya == 0)
    {
      kondisi_cahaya = "Nyalakan lampu";
    }else{
      kondisi_cahaya = "Matikan lampu";
    }

    if(POT>500){
      kondisi = "Kering, nyalakan motor";
      thing.call_endpoint("moisure");
    }else if (POT>400&&POT<500){

```

```
kondisi = "Normal";}
else if (POT<400){
kondisi = "basah";}
else if (POT<200){
kondisi = "Terlalu basah, berpotensi tanaman
mati";} }
}
```