

## Lampiran

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1. #define BLYNK_TEMPLATE_ID "TMPLjDDoU4Ks"
2.     #define BLYNK_DEVICE_NAME
"esp8266hidro" 3.
4. #define BLYNK_FIRMWARE_VERSION     "0.1.0"
5.#define BLYNK_PRINT Serial
6. #define APP_DEBUG
7.     #define
USE_NODE_MCU_BOARD 8.
9. #include "BlynkEdgent.h"
10.     #define SOUND_VELOCITY
0.034 11.
12. const int trigPin = 12;//12 D6
13. const int echoPin = 14;//14 D5
14. int pinPompa1 = 13; //D7
15.     int pinPompa2 = 15;
//D8 16.
17. int dataPompa1;
18. int dataPompa2;
19. const int ON = 0;
20.     const int OFF
= 1; 22.
23. long duration;
24.     float
distanceCm; 25.
26. float data_hcsr04;
27. float tinggi_air;
28. float data_kumulatif;
29. float data_rata;
30. int pengambilan;
31. int data_adc;
32. int set_level;
33. int set_ph;
34.     int
pernah,flag; 35.
36. float nilai_hcsr04() {
37.digitalWrite(trigPin, LOW);
38 delayMicroseconds(2);
39     digitalWrite(trigPin,
HIGH); 40
delayMicroseconds(10);
41 digitalWrite(trigPin, LOW);
42
43 duration = pulseIn(echoPin, HIGH);
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44 distanceCm = duration * SOUND_VELOCITY / 2;
45 delay(100);
46 return distanceCm;
47 }
48 // SWITCH Pompa 1
49 BLYNK_WRITE(V2) {
50 dataPompa1 = param.asInt();
51   Serial.print("Status Pompa1= ");
Serial.println(dataPompa1); 52 if (dataPompa1 == 1) {
53
//digitalWrite(pinPompa1,ON);
54 } else if (dataPompa1 == 0) {
55 //digitalWrite(pinPompa1,OFF);
56 }
57 }
58
59 // SWITCH Pompa2
60 BLYNK_WRITE(V3) {
61 dataPompa2 = param.asInt();
62 Serial.print("Status Pompa1= "); Serial.println(dataPompa2);
63 if (dataPompa2 == 1) {
64   digitalWrite(pinPompa2,
ON); 65 } else if (dataPompa2 ==
0) { 66 digitalWrite(pinPompa2,
OFF); 67 }
68 }
69
70 // slide level
71 int data_sl_level;
72 BLYNK_WRITE(V4) {
73 data_sl_level = param.asInt();
74   Serial.print("sl_level= ");
Serial.println(data_sl_level); 75 }
76
77 // slide ph
78 int data_sl_ph;
79 BLYNK_WRITE(V5) {
80 data_sl_ph = param.asInt();
81   Serial.print("sl_ph= ");
Serial.println(data_sl_ph); 82 }
83
84 WidgetLED led1(V6);
85
86 float baca_ph() {

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87 data\_kumulatif = 0.0;

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89 data_rata = 0.0;
90 pengambilan = 20;
91   for (int i = 0; i <
pengambilan; i++) 92 {
93   data_adc = analogRead(A0);
94   data_kumulatif = data_kumulatif + data_adc;
95   delay
(10); 96}
97 data_rata = data_kumulatif / pengambilan;
98 return data_rata;
99 }
100
101
102 void kontrol1() {
103 // _____ kontrol air V1 _____
104   set_level           =
data_sl_level; 105   if
(tinggi_air <= set_level) 106 {
107   digitalWrite(pinPompa1, ON);
108   } else if (tinggi_air >
set_level) 109 {
110   digitalWrite(pinPompa1,
OFF); 111 }
112}
113
114 void kontrol2()
115 {
116 // _____ kontrol air V2... _____
117 set_level = data_sl_level;
118 int selisih = 2;
119 int batas_bawah;
120 batas_bawah = set_level - selisih;
121 led1.off();
122   pernah
= 0; 123
124 // ----- kendali level -----
125 if (tinggi_air >= set_level)
126 {
127   do {
128   BlynkEdgent.run();
129   set_level = data_sl_level;
130   digitalWrite(pinPompa1, OFF);
131   data_hcsr04 = nilai_hcsr04();
132   tinggi_air = 24.0 - data_hcsr04;

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133   batas_bawah = set_level -
selisih; 134
135   Blynk.virtualWrite(V0, tinggi_air);
136   Blynk.virtualWrite(V1,
baca_ph()); 137
138   Serial.print("tinggi_loop="); Serial.println(tinggi_air);
139   Serial.print("sensor ph="); Serial.println(baca_ph());
140   if ( baca_ph() <= data_sl_ph)
141     { Serial.println("kurang");
142       led1.on();
143       if (pernah == 0) {
144         Blynk.logEvent("kirim", String("Sensor pH mendeteksi KURANG
NUTRISI"));
145         pernah
= 1; 146 }
147     }else{
148       pernah = 0;
149       led1.of
f(); 150 }
151 } while (tinggi_air >= batas_bawah);
152 }
153
154 else if (tinggi_air <
set_level) 155 {
156   do {
157     BlynkEdgent.run();
158     set_level = data_sl_level;
159     digitalWrite(pinPompa1, ON);
160     data_hcsr04 = nilai_hcsr04();
161     tinggi_air = 24.0 - data_hcsr04;
162     Blynk.virtualWrite(V0, tinggi_air);
163     Blynk.virtualWrite(V1, baca_ph());
164     Serial.print("tinggi_loop="); Serial.println(tinggi_air);
165     Serial.print("sensor ph="); Serial.println(baca_ph());
166     if ( baca_ph() <= data_sl_ph)
167       { Serial.println("kurang");
168         led1.on();
169         if (pernah == 0) {
170           Blynk.logEvent("kirim", String("Sensor pH mendeteksi KURANG
NUTRISI"));
171           pernah = 1;
172         }
173       }else{
174         pernah = 0;

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175     led1.off();
176     }
177     }
178     Serial.print("tinggi_loop="); Serial.println(tinggi_air);
179     } while (tinggi_air <=
set_level); 180 }
181 }
182
183
184 void setup()
185 {
186   Serial.begin(115200);
187   pinMode(trigPin, OUTPUT);
188   pinMode(echoPin, INPUT);
189   pinMode(pinPompa1, OUTPUT);
190   pinMode(pinPompa2, OUTPUT);
191   digitalWrite(pinPompa1, HIGH);
192   digitalWrite(pinPompa2, HIGH);
193   BlynkEdgent.begin();
194   delay(100);
195 }
196 }
197
198 void loop() {
199   BlynkEdgent.run();
200   // _____BacaSensor_____ - _____
201   data_hcsr04 = nilai_hcsr04();
202   tinggi_air = 24.0 - data_hcsr04;
203   float data_ph =
204   baca_ph();
205   Serial.print("data hcsr04= "); Serial.println(tinggi_air);
206   Serial.print("data ADC-pH= ");
207   Serial.println(data_ph); 207 // _____
208
209   Blynk.virtualWrite(V0, tinggi_air);
210   Blynk.virtualWrite(V1,
211   baca_ph());
212   kontrol2();

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